

DMQA Open Seminar

Image Denoising

2024. 05. 10

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Data Mining and Quality Analytics Lab



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- Data Mining & Quality Analytics Lab. (김성범 교수님)
- 석박통합 과정 (2022.03 ~ Present)

❖ Research Interest

- Computer Vision (Image Restoration, Scene Text Recognition)
- Self/Semi-supervised Learning

❖ Contact

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❖ Introduction

❖ Algorithms

- ① Supervised Learning
 - Paired Noisy-Clean Images
 - Unpaired Noisy-Clean Images
- ② Self-supervised Learning
 - Paired Noisy-Noisy Images
 - Single Noisy Image
 - Blind Spot Network
 - Deep Image Prior

❖ Conclusion

Introduction

Introduction

Definition

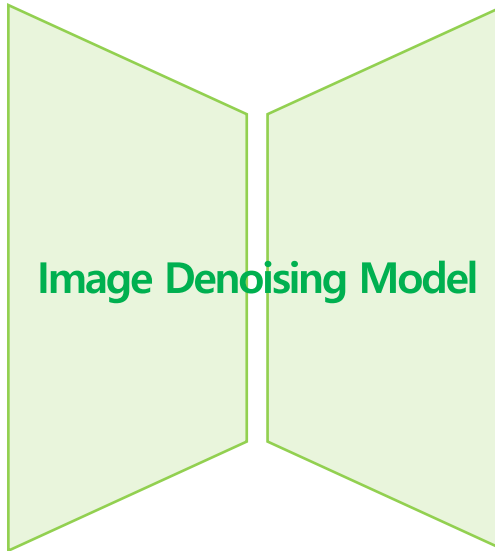
❖ Image Denoising이란?

- 이미지 내 존재하는 Noise를 제거하는 Task

[Input Image]



Noisy Image



[Output Image]



Clean Image

Noise 제거

Introduction

Goal

❖ Image Denoising의 목표

- “이미지 내 다양한 Noise에 강건한 모델 확립”

➤ 다양한 Noise 종류: Gaussian Noise, Poisson Noise, Salt-and-Pepper Noise ...



Introduction

Image Denoising in Real-World

❖ Real-World Image Denoising

- **Complex:** 단일 Noise가 아닌, 여러 Noise가 결합된 형태
 - Ex) Gaussian Noise + Salt-and-Pepper Noise + ...
- **Unknown:** 이미지 내 Noise의 종류는 알려지지 않음



Noise Type: ?



Noise Type: ?



Noise Type: ?

<https://media.cheggcdn.com/media/8c7/8c7f3063-bccd-49ef-a483-c160557d6ef4/phpAtYk4M.png>
https://www.inf.ufrgs.br/~eslgastal/AdaptiveManifolds/Application_Examples/Non-Local_Means_Denoising/kodim23-noise-std51.png
https://www.inf.ufrgs.br/~eslgastal/AdaptiveManifolds/Application_Examples/Non-Local_Means_Denoising/kodim23-noise-std51.png

Introduction

Taxonomy

❖ Overall Taxonomy

- ① **Computer Vision Algorithm:** 학습 없이 수리적 알고리즘 활용
- ② **Supervised Learning:** Noisy Image (X) $\leftrightarrow$ Clean Image (Y)에 대하여 학습
- ③ **Self-supervised Learning:** Clean Image (Y) 없이 Noisy Image (X) 로만 학습



Noisy Image



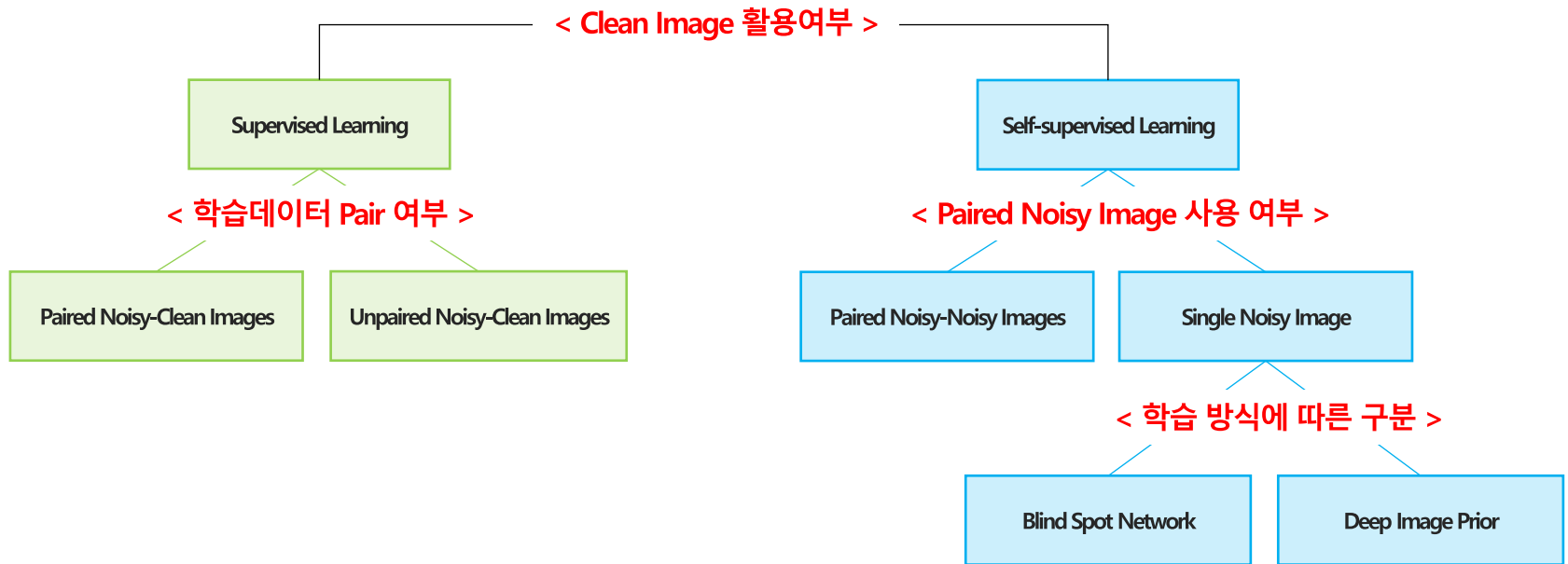
Clean Image

	Computer Vision Algorithm	Supervised Learning	Self-supervised Learning
학습여부	X	O	O
Clean Image 필요 여부	X	O	X

Introduction

Taxonomy

❖ Image Denoising Taxonomy



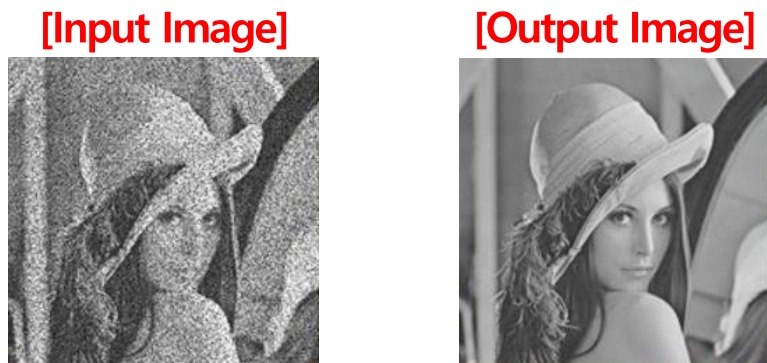
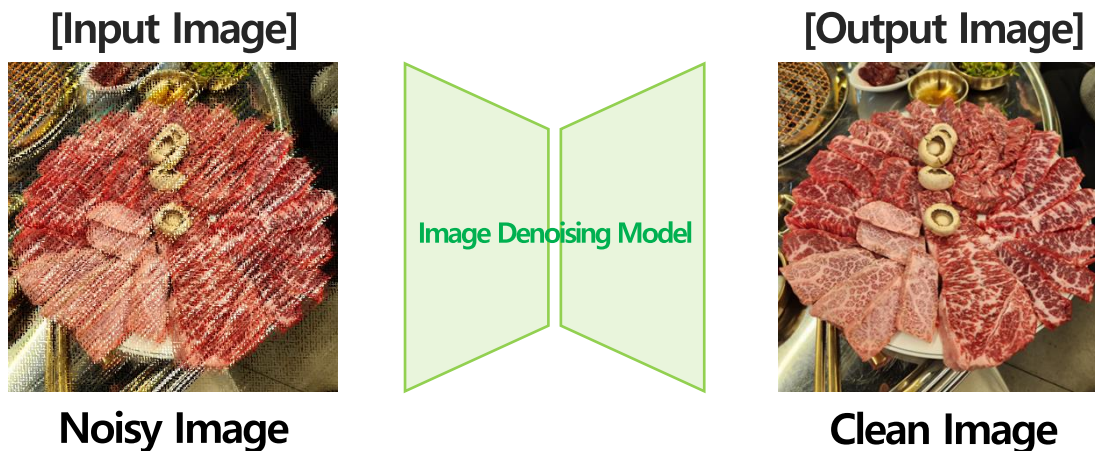
Algorithms (1)

[Supervised Learning]

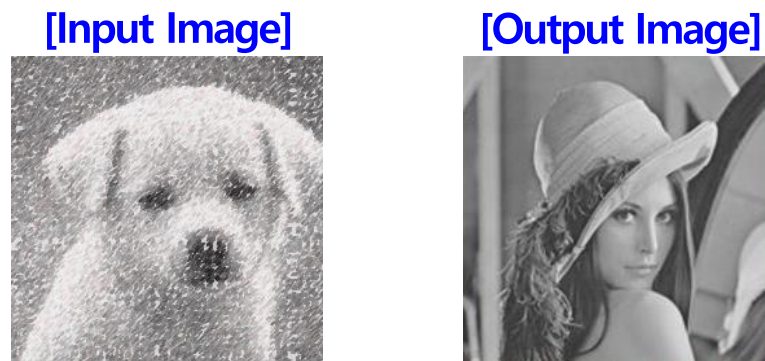
Algorithms: Supervised Learning

Supervised Learning-based Image Denoising

- ❖ **Supervised Learning : Noisy Image와 Clean Image를 모두 활용**



Paired Noisy-Clean Images

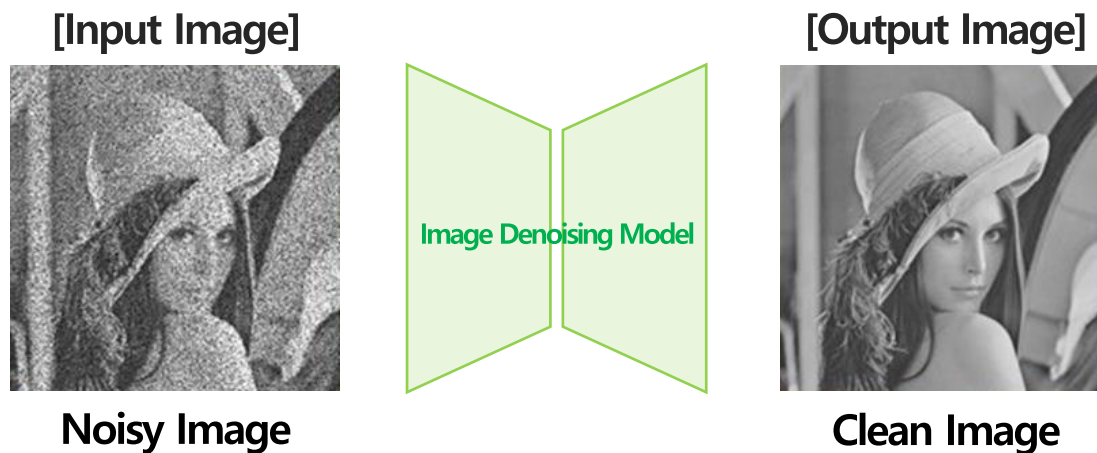


Unpaired Noisy-Clean Images

Algorithms: Supervised Learning

Supervised Learning (1): Paired Noisy-Clean Images

❖ Paired Noisy-Clean Images



***** 한계 *****

“ 동일한 장면에 대한 서로 다른 이미지는 현실에 거의 존재하지 않음 ”

Algorithms: Supervised Learning

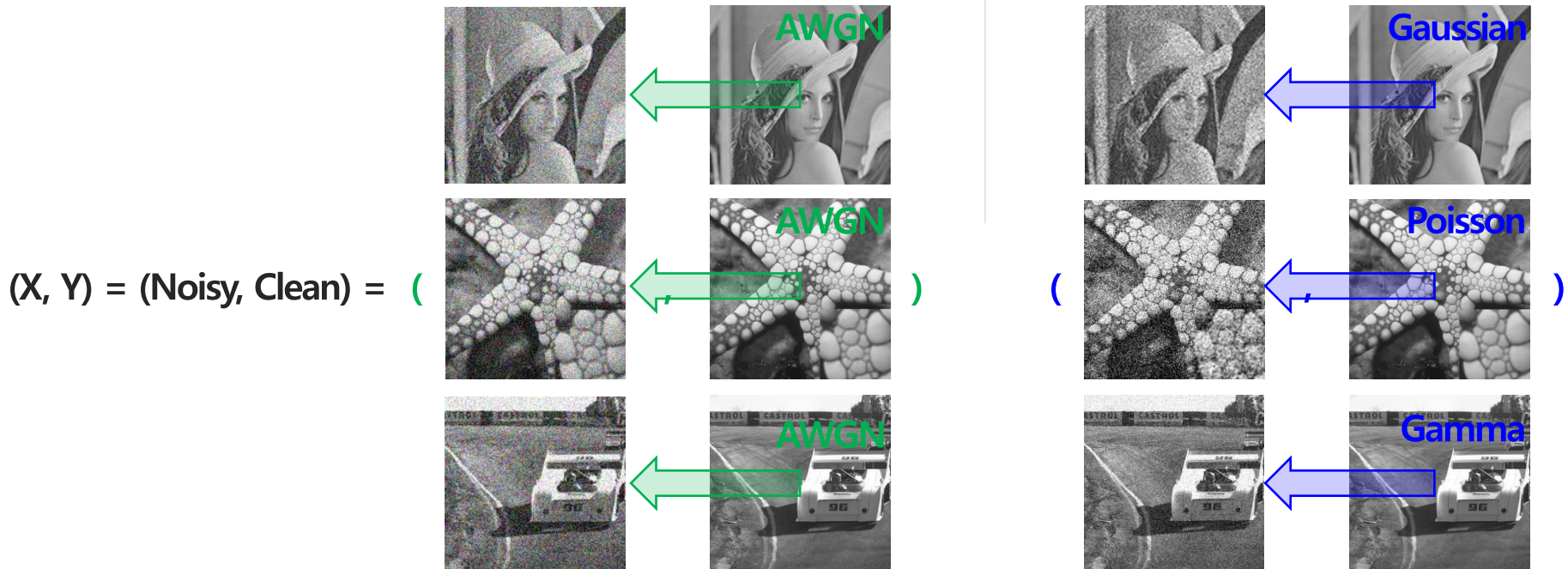
Supervised Learning (1): Paired Noisy-Clean Images



❖ Paired Noisy-Clean Images

[학습 데이터를 합성하여 해결]

★ Clean Image에 Noise를 인위적으로 부여 → Noisy 이미지 획득★



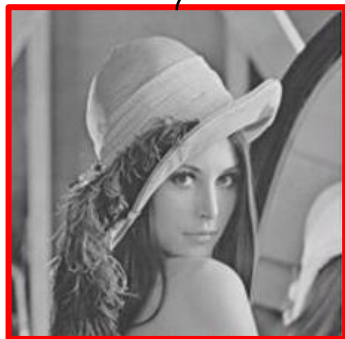
Algorithms: Supervised Learning

Supervised Learning (1): Paired Noisy-Clean Images



❖ Paired Noisy-Clean Images (1/2): Jain et al (2008, NIPS)

- Denoising에 딥러닝을 적용한 첫번째 방법론
 - 입력: Noisy Image / Output: Clean Image



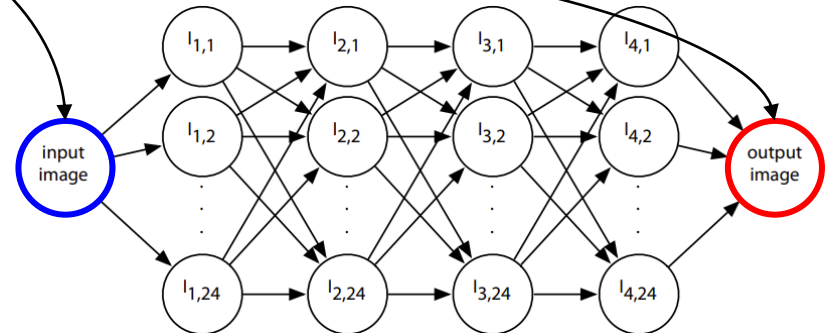
Clean Image



Noise



Noisy Image



$$\min_{\phi} \sum_i (\underbrace{x_i}_{\text{Clean Image}} - \underbrace{F_{\phi}}_{\text{Denoising Model}}(\underbrace{n(x_i)}_{\text{Noisy Image}}))^2$$

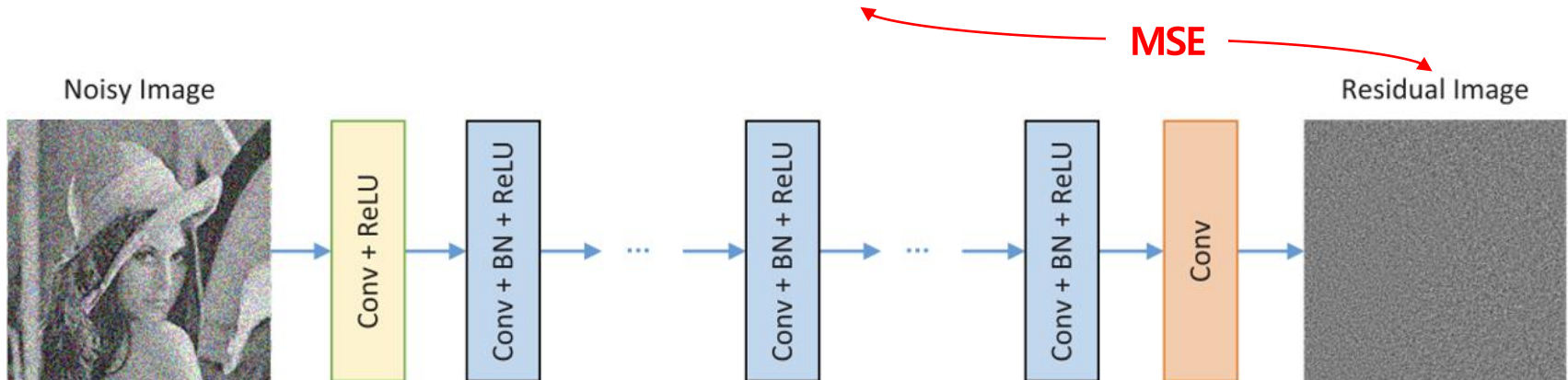
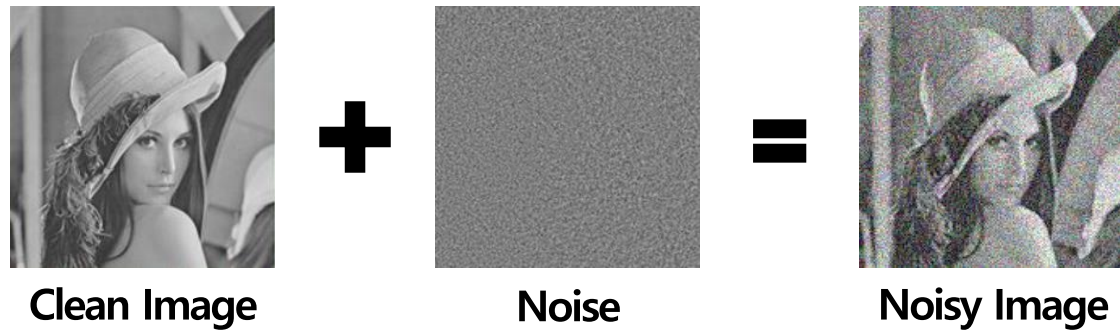
Algorithms: Supervised Learning

Supervised Learning (1): Paired Noisy-Clean Images



❖ Paired Noisy-Clean Images (2/2): DnCNN (2017, TIP)

- Train: 이미지를 직접 Denoising하는 것이 아닌, 이미지에서 Noise를 분리하는 것을 학습
 - 입력: Noise Image / Output: **Residual Map**
 - 학습 목표의 명확성: Noise 제거 및 이미지 생성 → 제거해야 할 Noise만 학습



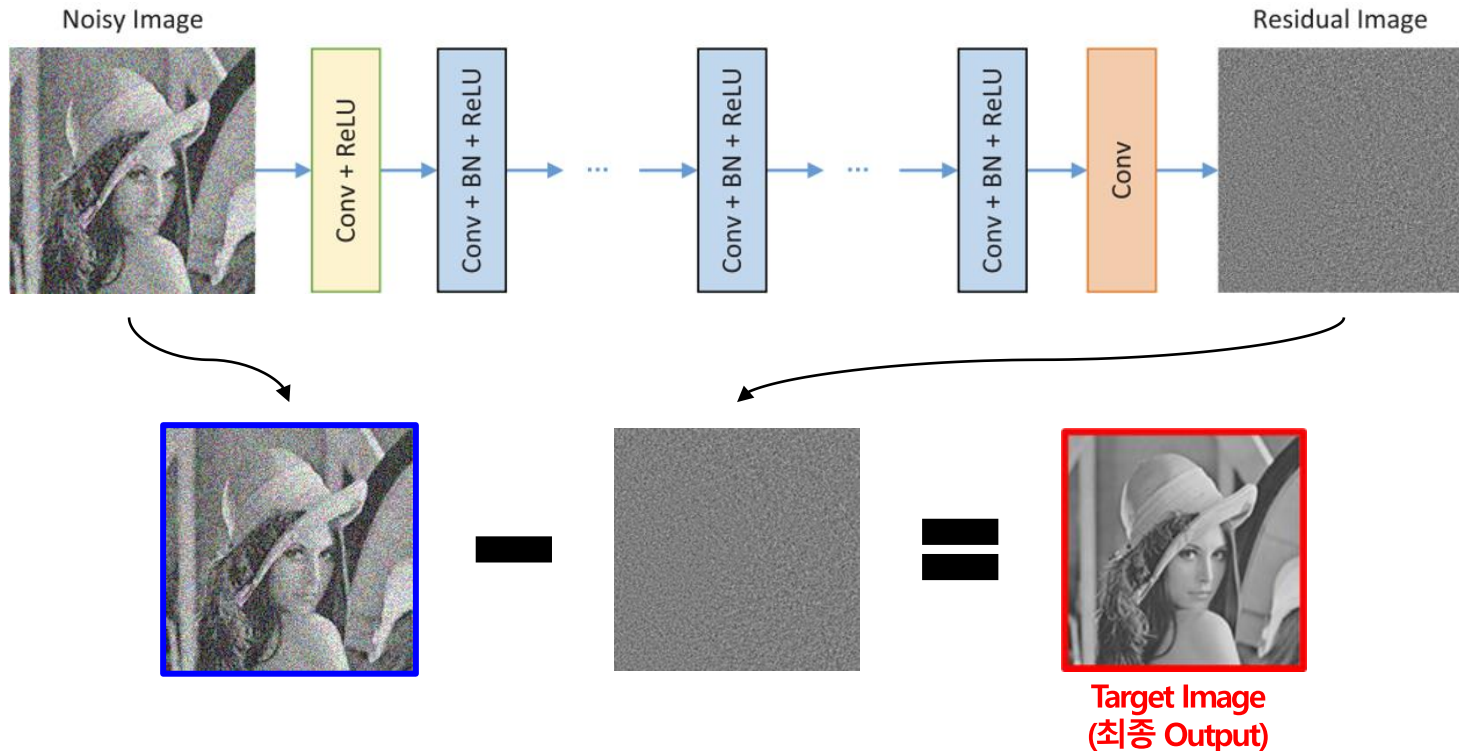
Algorithms: Supervised Learning

Supervised Learning (1): Paired Noisy-Clean Images



❖ Paired Noisy-Clean Images (2/2): DnCNN (2017, TIP)

- Inference: 기존 Noisy 이미지에서 Residual Map을 빼주어 최종 Clean Image 생성
 - ① Noisy 이미지를 DnCNN에 넣어 Residual Image 산출
 - ② 최종적인 Clean Image = Noisy 이미지 - Residual Image



Algorithms: Supervised Learning

Supervised Learning (2): Unpaired Noisy-Clean Images



❖ Unpaired Noisy-Clean Images

실제 이미지들을 활용하여 Real-World Noise를 효과적으로 활용하자!

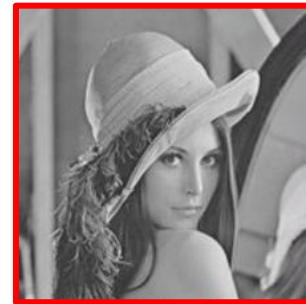


Clean Image

VS

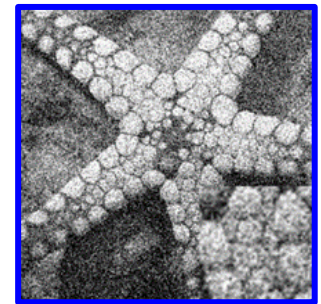


Noisy Image



Clean Image

VS



Noisy Image

Paired → **Unpaired**

실제 Clean & 합성 Noisy 이미지를 활용

Clean & Noisy 이미지가 대응

Real-World Noise 학습에 어려움 존재

실제 Clean & 실제 Noisy 이미지를 활용

Clean & Noisy 이미지가 대응되지 않음

Real-World Noise 학습 가능

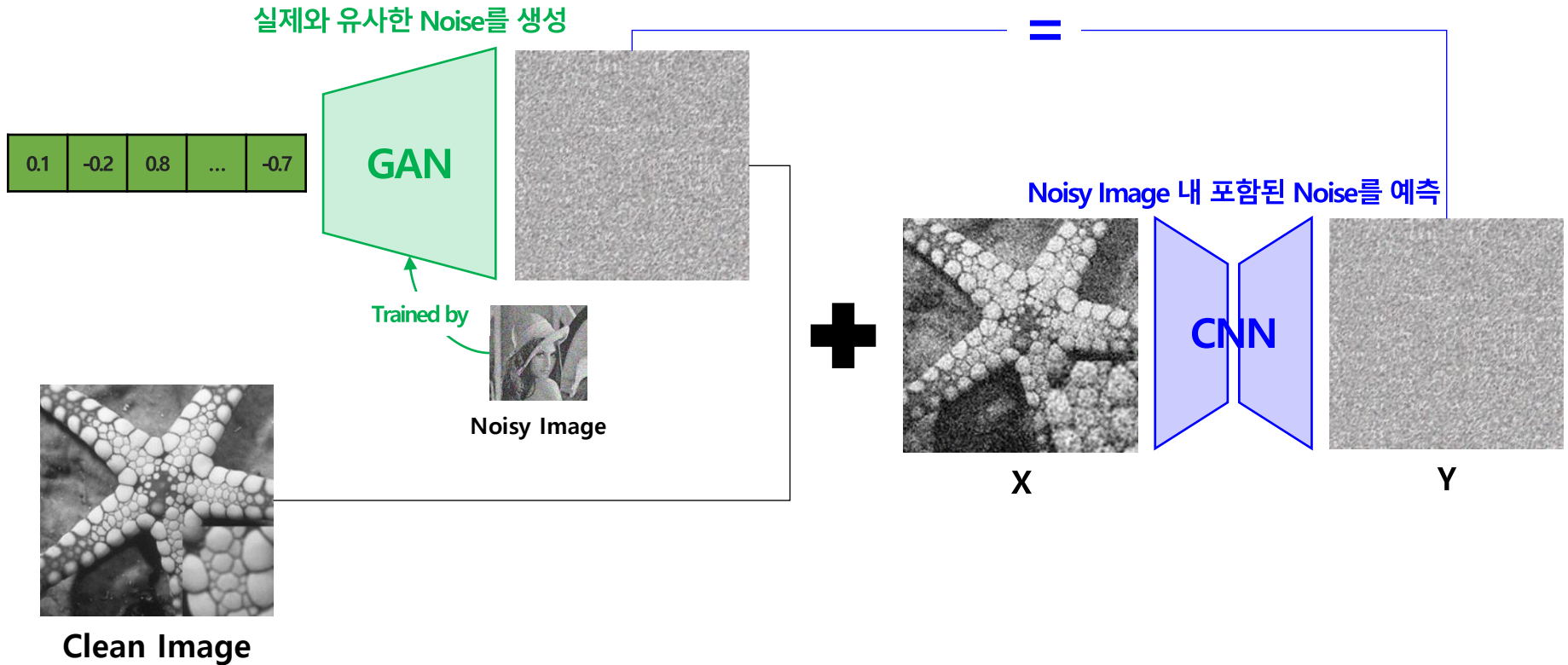
Algorithms: Supervised Learning

Supervised Learning (2): Unpaired Noisy-Clean Images



❖ Unpaired Noisy-Clean Images: GCBD (2018, CVPR)

- GCBD: GAN-CNN based Blind Denoiser (GAN 및 CNN의 2-stage 구조로 구성)



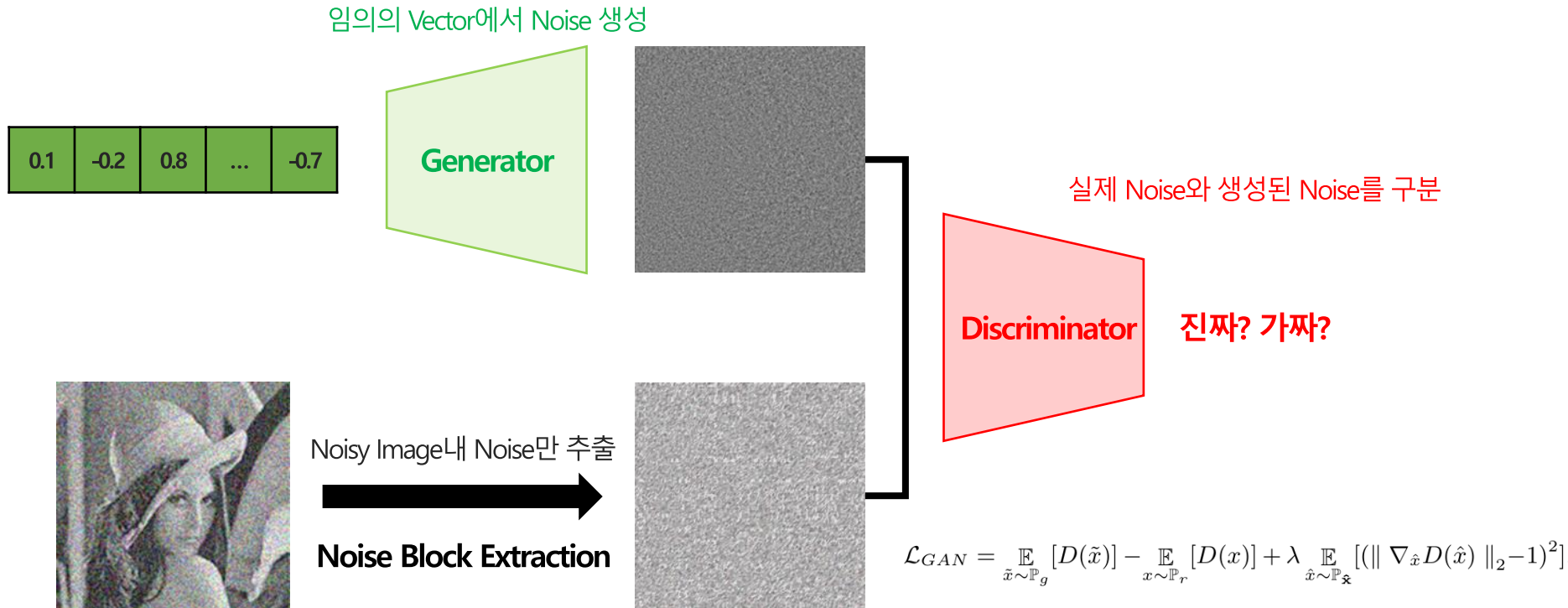
Algorithms: Supervised Learning

Supervised Learning (2): Unpaired Noisy-Clean Images



❖ Unpaired Noisy-Clean Images: GCBD (2018, CVPR)

- Phase1 - GAN: Generator와 Discriminator가 적대적으로 학습 (WGAN-GP 기반)



Algorithms: Supervised Learning

Supervised Learning (2): Unpaired Noisy-Clean Images



❖ Unpaired Noisy-Clean Images: GCBD (2018, CVPR)

- Phase1 - GAN: Generator와 Discriminator가 적대적으로 학습 (WGAN-GP 기반)

[Noise Block Estimation]

Noisy 이미지만으로 Noise 패치 추출 (Hand-crafted 방식)

- ① 두 패치 내 픽셀들의 평균 및 분산 차이가 아래 범위를 만족 $\rightarrow p_i$ 필터링

$$|Mean(q_j^i) - Mean(p_i)| \leq \mu \cdot Mean(p_i)$$

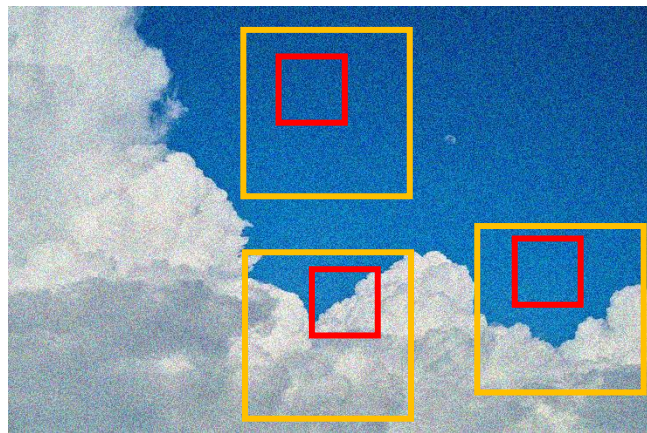
$$|Var(q_j^i) - Var(p_i)| \leq \gamma \cdot Var(p_i)$$

“ 위 조건을 만족하는 p_i : 변화가 거의 없는 패치 (ex. 벽, 하늘 등) ”

- ② 평균 픽셀만큼 빼주기

$$Noise_i = p_i - Mean(p_i)$$

“ 변화가 거의 없는 패치 = 모든 픽셀이 유사 = 평균: 각 Pixel의 Content 대변 ”



큰 패치 p_i 와 p_i 내 작은 패치인 q_j^i 를 활용

p_i : 전체 이미지를 Sliding

q_j^i : p_i 내부를 Sliding

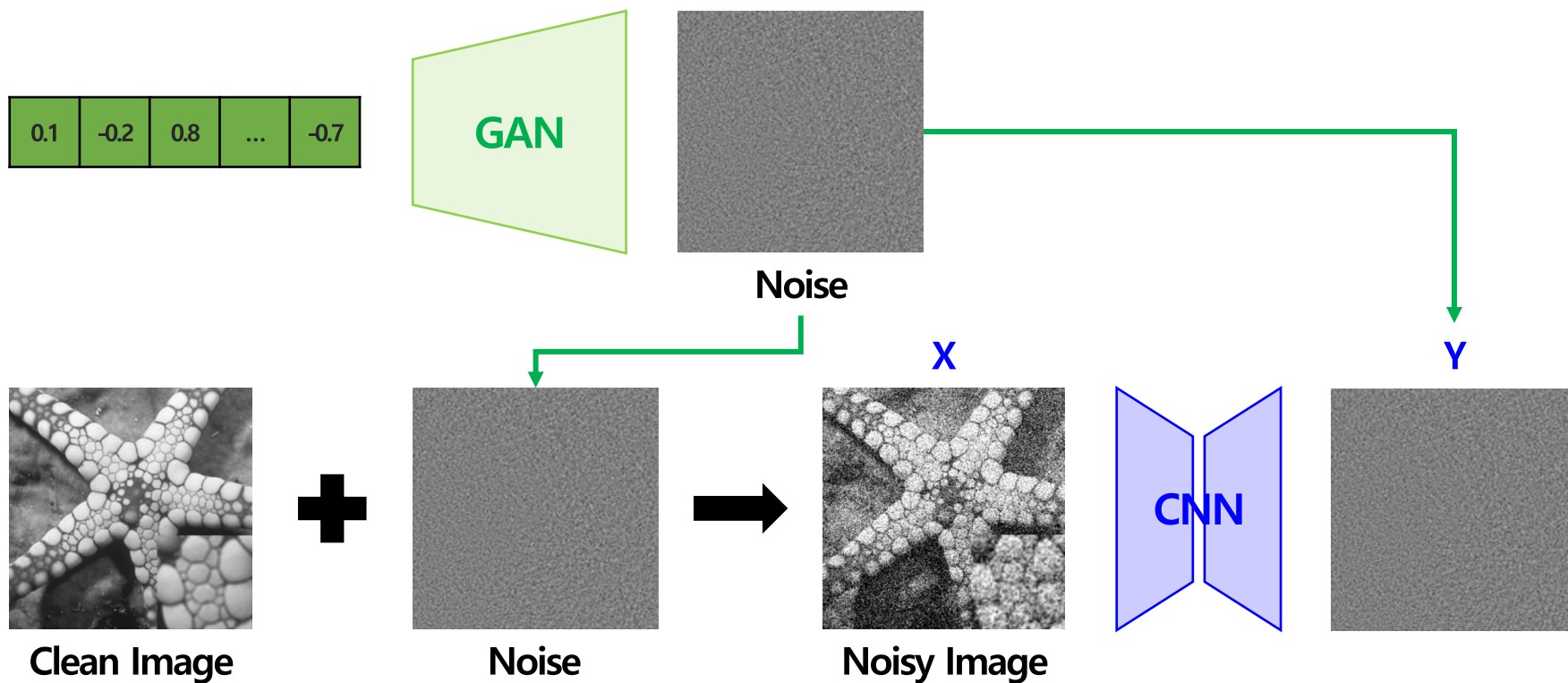
Algorithms: Supervised Learning

Supervised Learning (2): Unpaired Noisy-Clean Images



❖ Unpaired Noisy-Clean Images: GCBD (2018, CVPR)

- Phase2 - CNN: Noisy Image(Clean Image + Noise)에 포함된 Noise를 예측
 - GAN에서 Noise를 생성한 후, Clean Image와 결합하여 Noisy Image 생성
 - 서로 대응되는 Noisy-Clean Image Pair를 만든 후, DnCNN 구조를 기반으로 학습



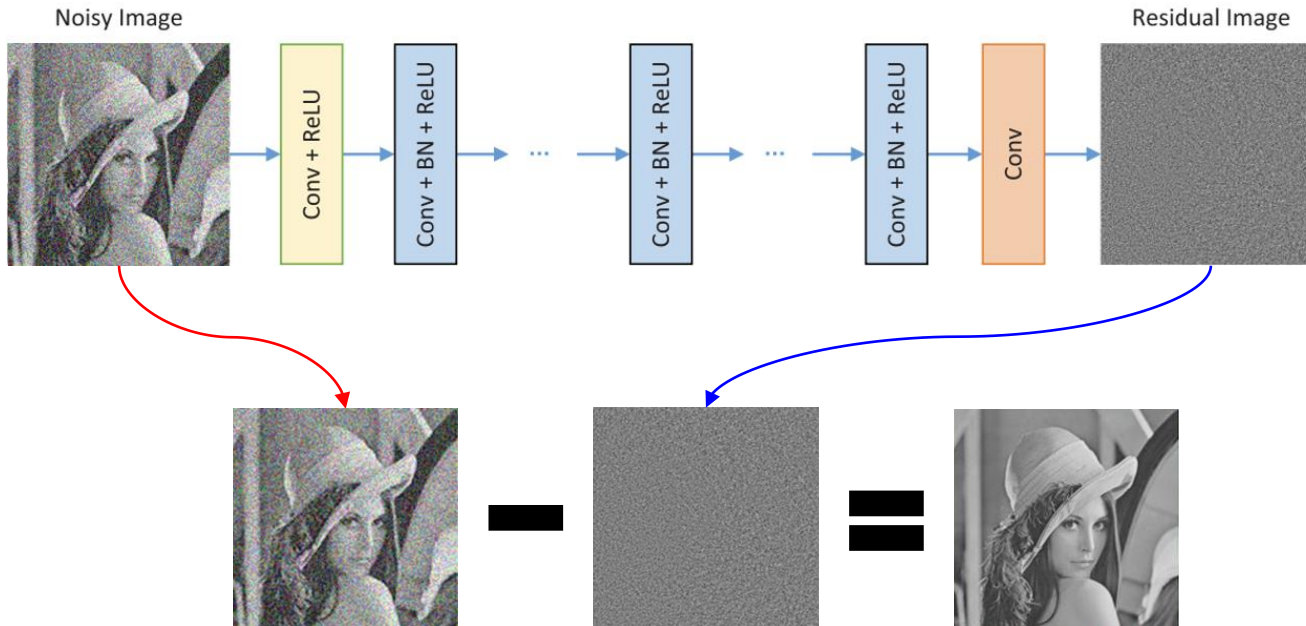
Algorithms: Supervised Learning

Supervised Learning (2): Unpaired Noisy-Clean Images



❖ Unpaired Noisy-Clean Images: GCBD (2018, CVPR)

- Inference: Noisy 이미지 내 Noise를 예측
 - 최종 Output = Noisy Image – 예측된 Noise



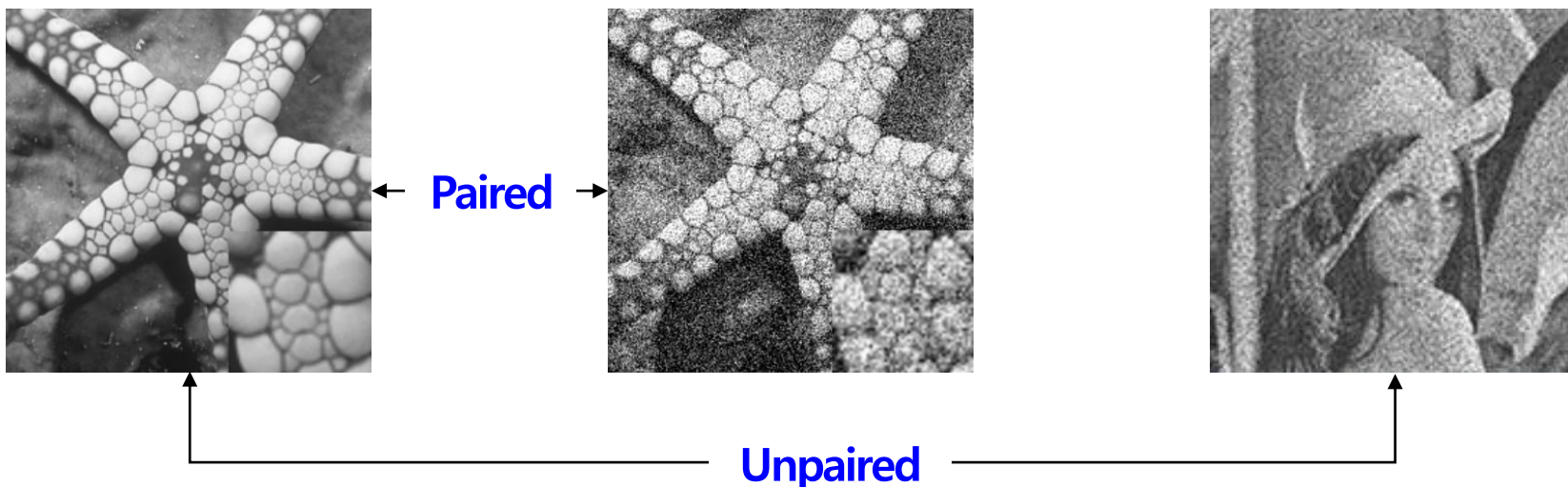
Algorithms: Supervised Learning

Summary



❖ Supervised Learning

- **Paired Noisy-Clean Images**: 실제 Clean Image로부터 합성 Noisy Image를 생성하여 Pair 생성
- **Unpaired Noisy-Clean Images**: Pair가 아닌 실제 Clean 및 실제 Noisy 이미지를 활용
 - Noise 추정 모델에 대한 필요성 제거



“ 여전한 제약: Clean Image가 필요하다 ”

Algorithms (2)

[Self-supervised Learning]

Algorithms: Self-supervised Learning

Self-supervised Learning-based Image Denoising

❖ Supervised Learning → Self-supervised Learning

- 핵심: 현실에서는 Noise가 없는 Clean Image를 구하는 것이 가장 어려움
- Motivation: Noisy Image만 있는 상황에서 Denoising 모델을 학습할 수는 없을까?

“ Clean 이미지 없이, 오직 Noisy 이미지들만으로 학습해보자. ”



Noisy Image

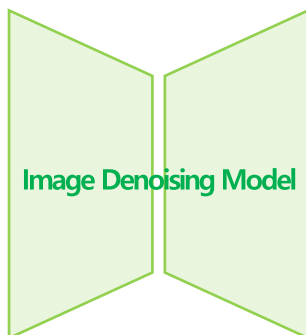


Image Denoising Model



Clean Image

Supervised → **Self-supervised**

Clean(Y) 및 Noisy(X) Image를 모두 활용

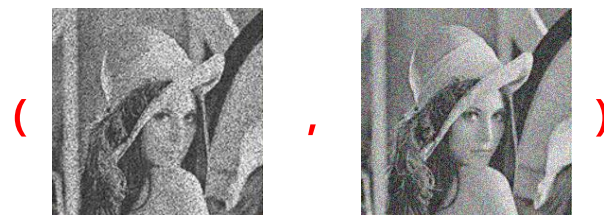
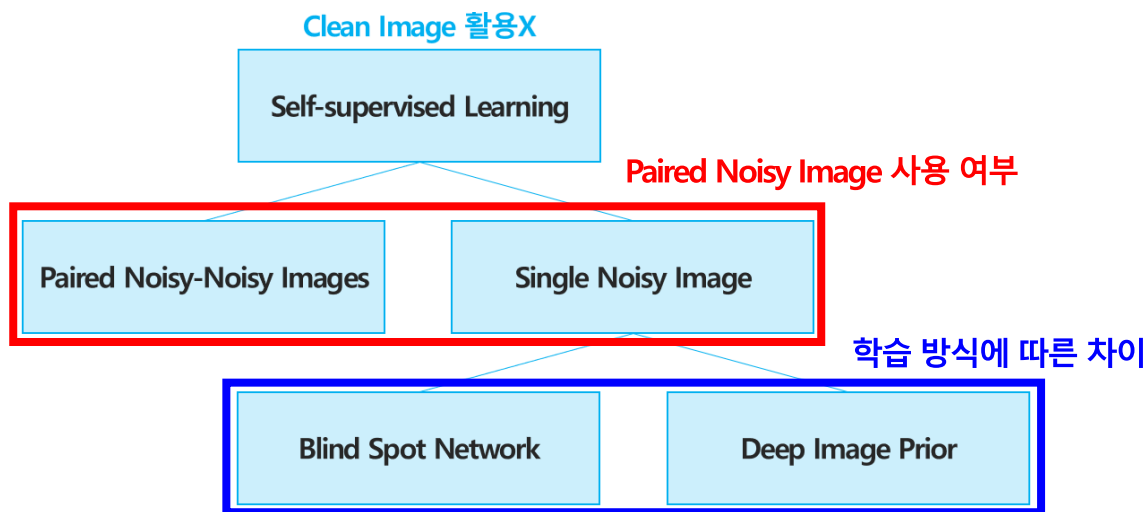
Noisy(X) Image만 활용

Algorithms: Self-supervised Learning

Self-supervised Learning-based Image Denoising

❖ Self-supervised Learning

- Paired Noisy-Noisy Images: 동일한 장면의 Noisy Image 쌍으로 모델을 학습
- Single Noisy Image: 오직 Noisy 이미지만으로 모델 학습



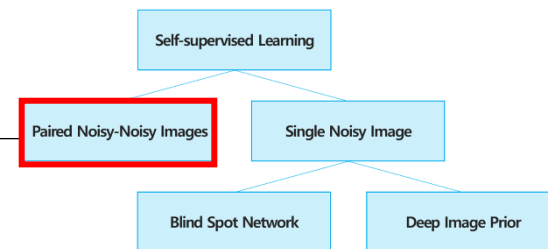
Paired Noisy-Noisy Images



Single Noisy Image

Algorithms: Self-supervised Learning

Self-supervised Learning (1): Paired Noisy-Noisy Images

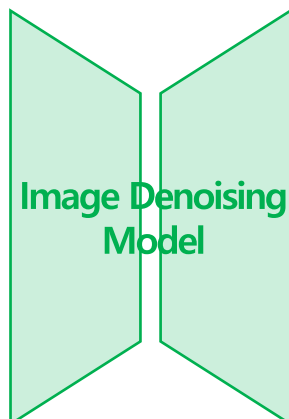


❖ Paired Noisy-Noisy Images: Noise2Noise (2018, ICML)

- Clean Image 없이 오직 Noisy Image Pair만으로 모델을 학습
- Noise Image①의 복원결과가 Noisy Image②가 되도록 학습



Noisy Image①
(X)



Restored Noisy Image①

↔ 유사



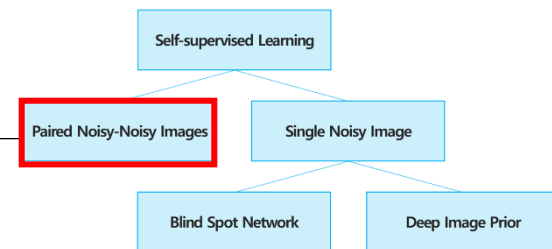
Noisy Image②
(Y)

★ 동일한 장면에 해당하는 서로 다른 Noisy Image를 필요로 함 ★

$$\arg \min_{\theta} \mathbb{E}_{\mathbf{x}, \mathbf{y}, \mathbf{z}} \|f_{\theta}(\mathbf{y}) - \mathbf{z}\|_2^2$$

Algorithms: Self-supervised Learning

Self-supervised Learning (1): Paired Noisy-Noisy Images



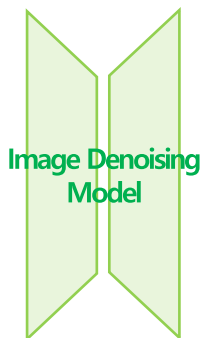
❖ Paired Noisy-Noisy Images: Noise2Noise (2018, ICML)

< Ill-posed Problem >

Noisy Image에 정답이 가능한 Clean Image는 하나의 형태가 아님



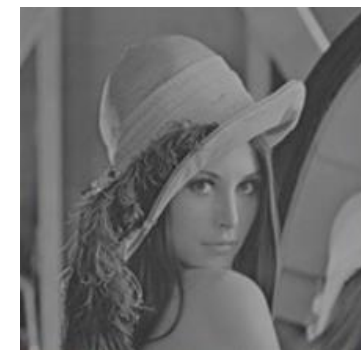
Noisy Image①
(Input)



Clean Image①
(Output)



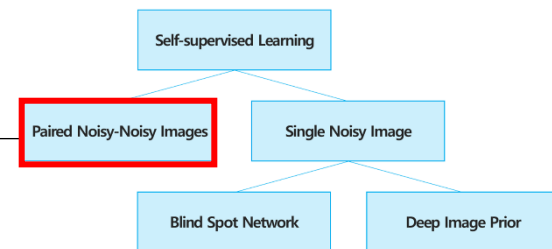
Clean Image②
(Output)



Clean Image③
(Output)

Algorithms: Self-supervised Learning

Self-supervised Learning (1): Paired Noisy-Noisy Images

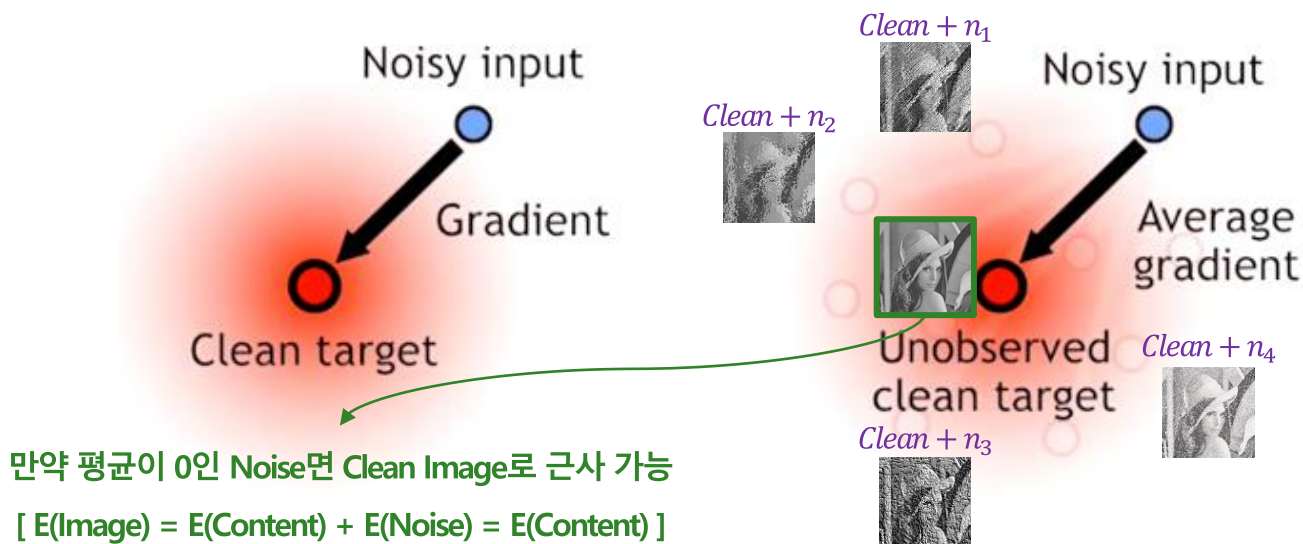


❖ Paired Noisy-Noisy Images: Noise2Noise (2018, ICML)

< Ill-posed Problem >

Noisy Image에 정답이 가능한 Clean Image는 하나의 형태가 아님

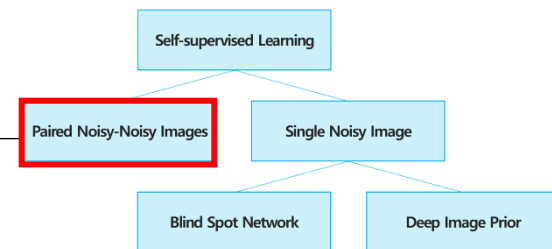
“ L2 Loss로 학습 시, 정답이 가능한 여러 Clean Image 중 평균값으로 학습 ”



Target이 되는 Noisy Image도 가능한 Clean Image 중 하나이다.

Algorithms: Self-supervised Learning

Self-supervised Learning (1): Paired Noisy-Noisy Images



❖ Paired Noisy-Noisy Images: Noise2Noise (2018, ICML)

- 왜 L2 Loss는 평균이 최적일까?

$$L(\hat{y}) = \frac{1}{n} \sum_{i=1}^n \underbrace{(\hat{y} - y_i)^2}_{\text{가능한 여러 Clean Image}} \quad \text{L2 Loss}$$

L2 Loss를 최소화하는 최적값

$$\Rightarrow \frac{d}{d\hat{y}} L(\hat{y}) = \frac{d}{d\hat{y}} \left(\frac{1}{n} \sum_{i=1}^n (\hat{y} - y_i)^2 \right) = \frac{2}{n} \sum_{i=1}^n (\hat{y} - y_i) = 0 \quad \text{미분}=0$$

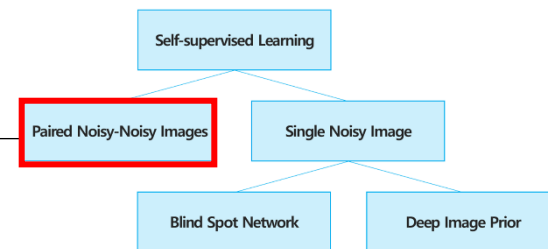
$$\Rightarrow \sum_{i=1}^n \hat{y} = \sum_{i=1}^n y_i$$

$$\Rightarrow n\hat{y} = \sum_{i=1}^n y_i$$

$$\Rightarrow \hat{y} = \frac{1}{n} \sum_{i=1}^n y_i \quad \text{L2 Loss의 최적값: 여러 데이터 포인트들의 평균}$$

Algorithms: Self-supervised Learning

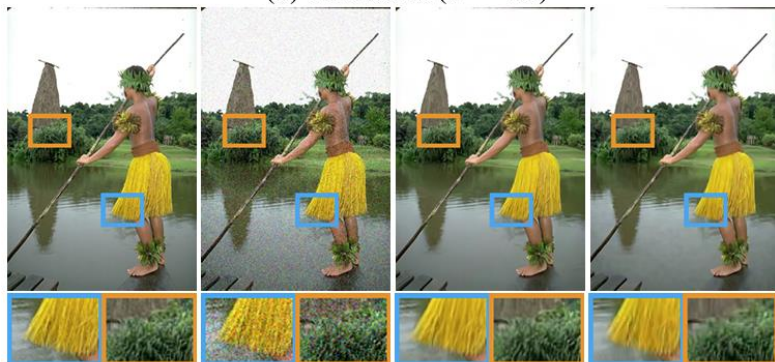
Self-supervised Learning (1): Paired Noisy-Noisy Images



❖ Paired Noisy-Noisy Images: Noise2Noise (2018, ICML)

- Noise2Noise: 평균이 0이 아닌 Noise에서 L2 Loss는 어려움을 겪음
 - 상황에 따라 L1 Loss가 효과를 보이는 경우도 존재 (Task에 따라 Loss 선택의 중요성)
 - * L1 Loss의 최적: 중간값

(a) Gaussian ($\sigma = 25$)



(b) Poisson ($\lambda = 30$)



GT Input Ours Comparison

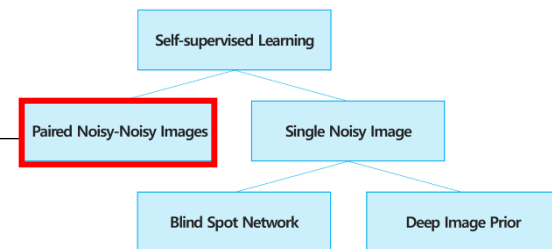
[Text Removal]



Text Removal: 주어진 픽셀과 전혀 색상의 Text를 제거
이상치에 민감한 평균보다, 이상치에 강건한 중간값이 우수

Algorithms: Self-supervised Learning

Self-supervised Learning (1): Paired Noisy-Noisy Images



❖ Paired Noisy-Noisy Images: Noise2Noise (2018, ICML)

- Noise2Noise: 평균이 0이 아닌 Noise에서 L2 Loss는 어려움을 겪음
 - 상황에 따라 L1 Loss가 효과를 보이는 경우도 존재 (Task에 따라 Loss 선택의 중요성)
 - * L1 Loss의 최적: 중간값

① Noise에 대한 가정 불필요

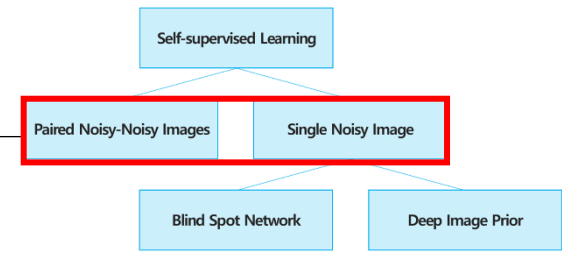
② Noise 추정 모델 불필요

③ 동일한 장면에 대한 Noisy-Noisy Pair 구축이 매우 어려움

④ Noise 특성에 따른 Loss 선택의 어려움

Algorithms: Supervised Learning

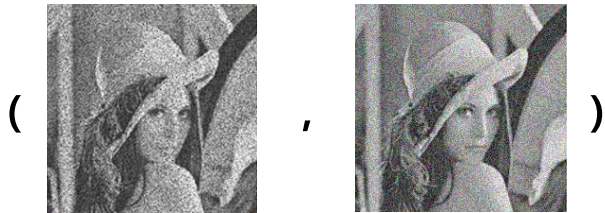
Definition for Single Noisy Image



❖ Paired Noisy-Noisy Images → Single Noisy Image

- Paired Noisy-Noisy Images: 학습 데이터 쌍 (Noisy Pair) 구축에 어려움이 존재

“ 하나의 Noisy Image 만으로 학습 할 수는 없을까? ”



Paired Noisy-Noisy Images

Noisy Pair 구축에 어려움 존재

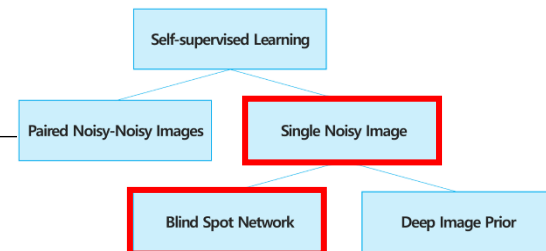


Single Noisy Image

Noisy Pair 없이 학습 가능

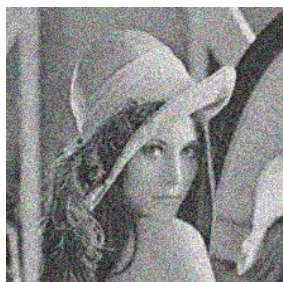
Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



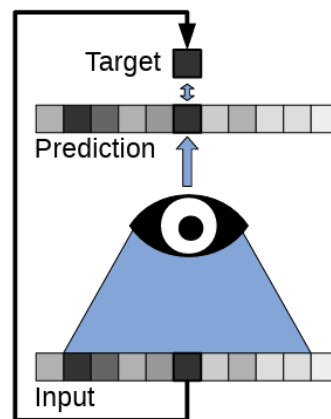
❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Blind Spot Network (BSN): 입력 이미지에서 특정 영역을 주변 정보로 복원하면서 학습
 - 이때, 자기 자신에 대한 픽셀 값을 “보지 못하게” 모델링 한다는 특징을 가짐

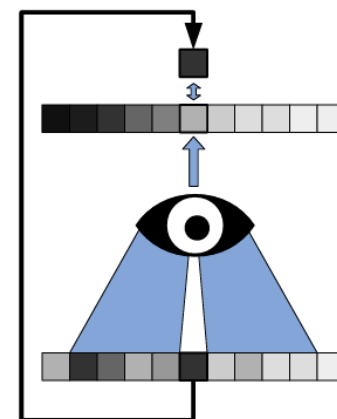


[특정 픽셀을 가린 이미지]

[특정 픽셀을 채움]



[기존 Convolution Network]

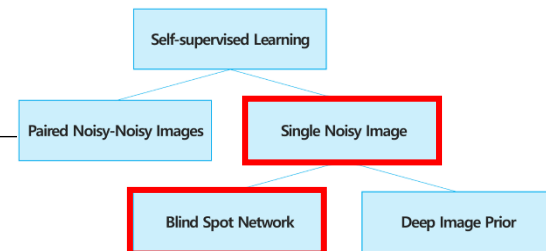


[Blind Spot Network]

“ 가려진 Pixel을 주변 정보만을 활용하여 예측 ”

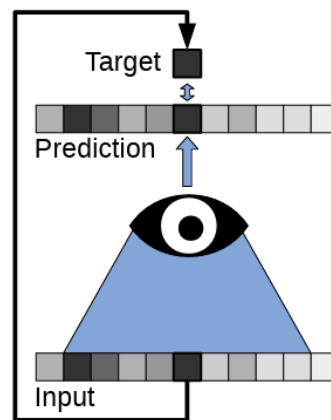
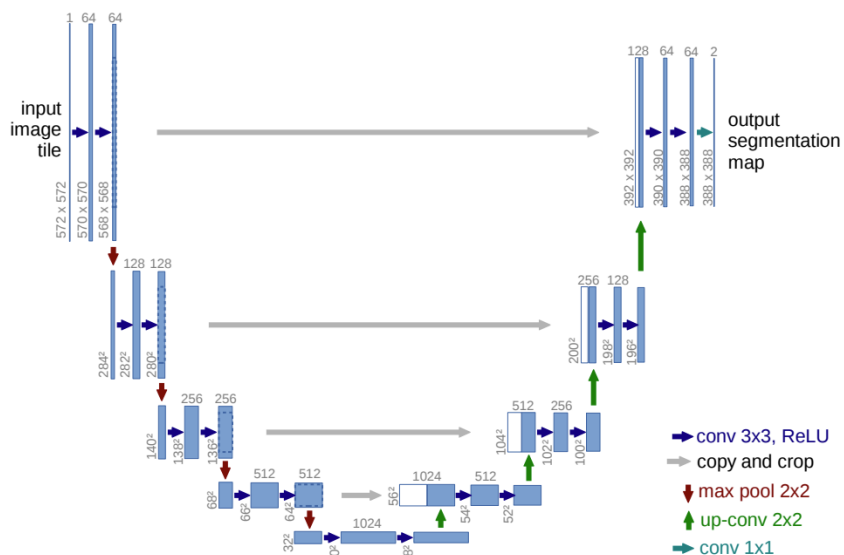
Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network

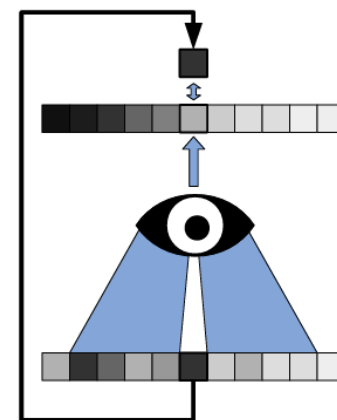


❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Blind Spot Network (BSN): 입력 이미지에서 특정 영역을 주변 정보로 복원하면서 학습
 - 이때, 자기 자신에 대한 픽셀 값을 “보지 못하게” 모델링 한다는 특징을 가짐



[기존 Convolution Network]

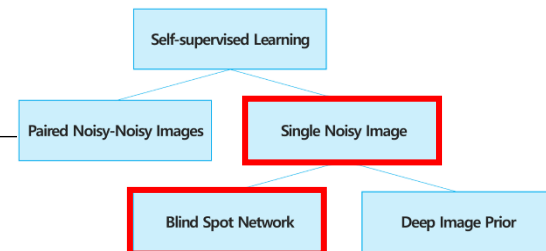


[Blind Spot Network]

“ 모델 내 모든 Conv Layer는 모두 BSN으로 구성 ”

Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Noise2Void: Image는 Signal과 Noise의 조합으로 구성



Noisy Image

=

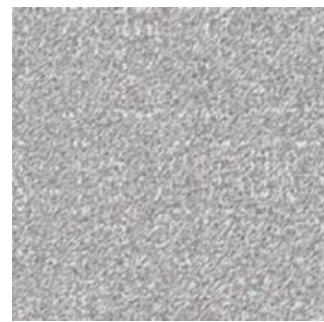


Signal

가정①

Signal은 픽셀 간 독립적이지 않음

+



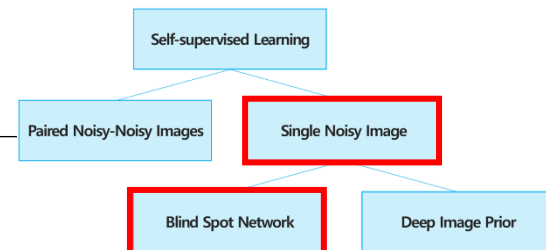
Noise

가정②

Noise는 픽셀 간 독립

Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network

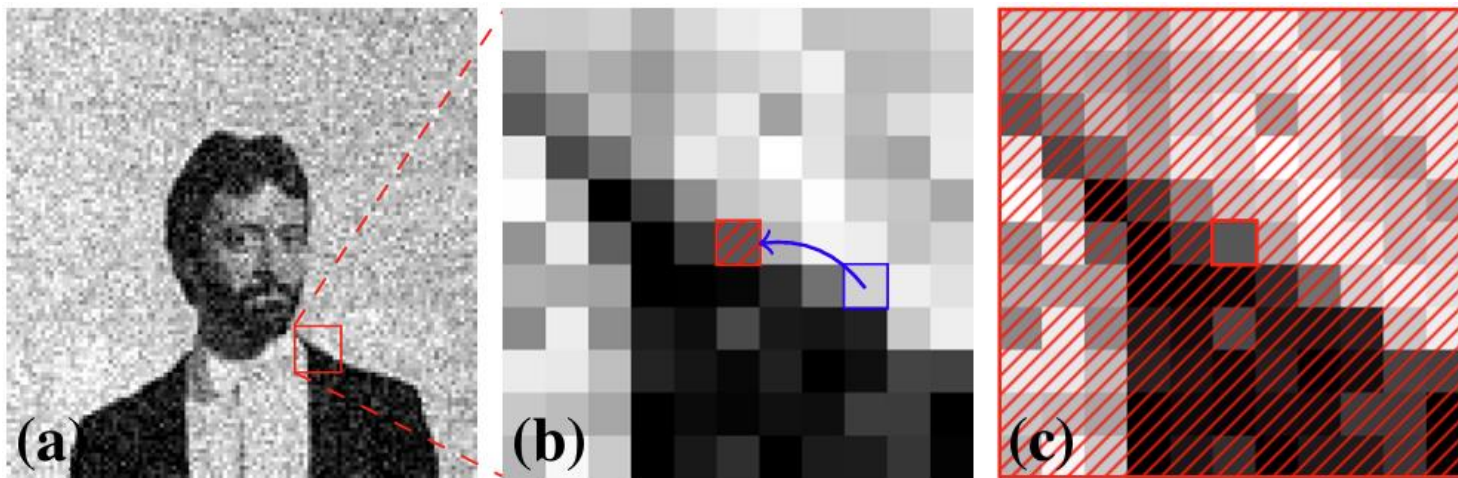


❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Noise2Void: Blind Spot Network를 활용하여 Denoising을 수행
 - ① Pixel Masking: Input Image 내 특정 N개 픽셀을 주변 픽셀 값으로 대체
 - ② BSN: 해당 이미지를 BSN을 통과
 - ③ Loss 산출: N개 픽셀에 대해서 Loss 산출

$$\arg \min_{\theta} \sum_j \sum_i L \left(f(\tilde{x}_{\text{RF}(i)}^j; \theta), x_i^j \right).$$

j번째 이미지 내 Masking 된 픽셀 i

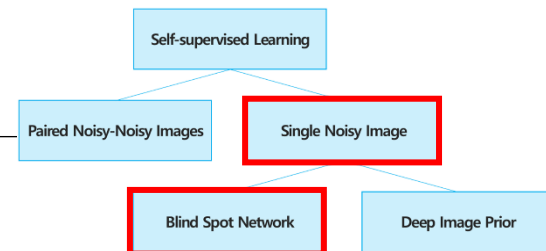


(a), (b): Pixel Masking
특정 Random 픽셀 값을 주변 값으로 대체

(c): BSN
주변 픽셀값만으로 자기 자신의 픽셀값 예측

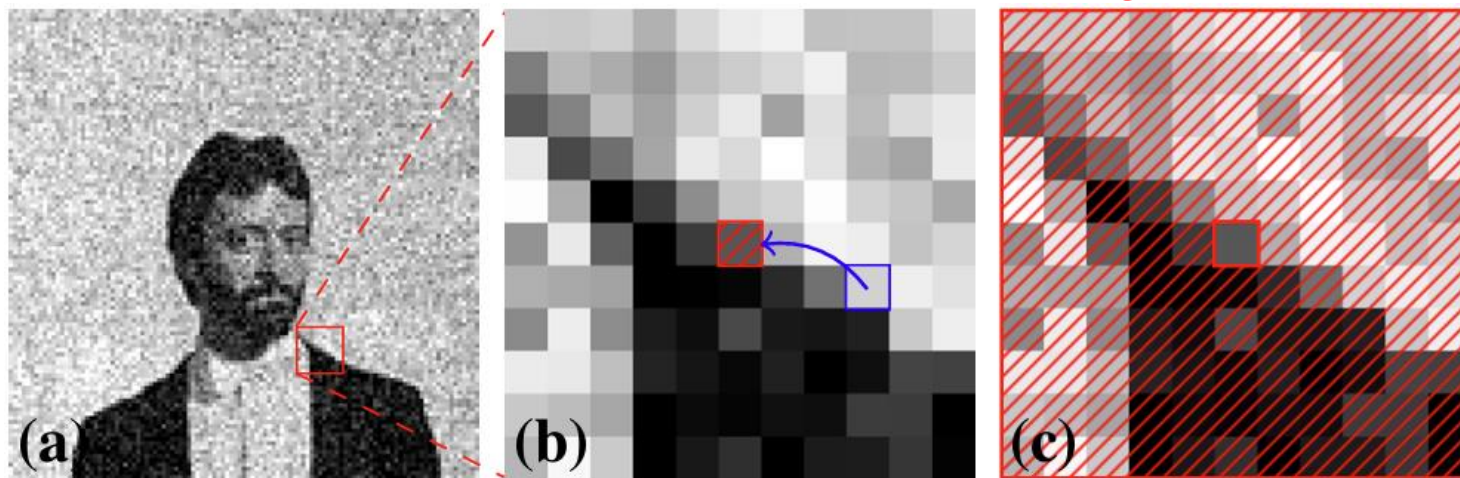
Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



❖ Blind Spot Network: Noise2Void (2019, CVPR)

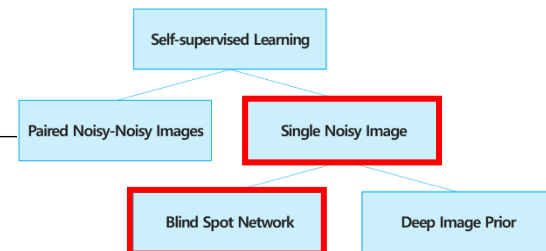
- Why BSN is Effective?: Center Pixel을 Masking하여 Identity Mapping 방지 가능
 - Signal → 주변 픽셀과 종속적 → 주변 픽셀만으로 복원 가능
 - Noise → 주변 픽셀과 독립적 → 주변 픽셀 정보로는 복원되지 않음



“ 단점: 가장 중요한 자기 자신 정보를 활용하지 않기에, 충분한 정보 활용이 어려움 ”

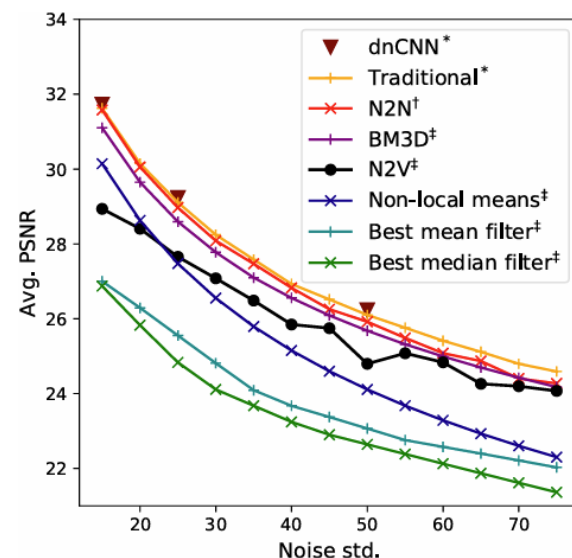
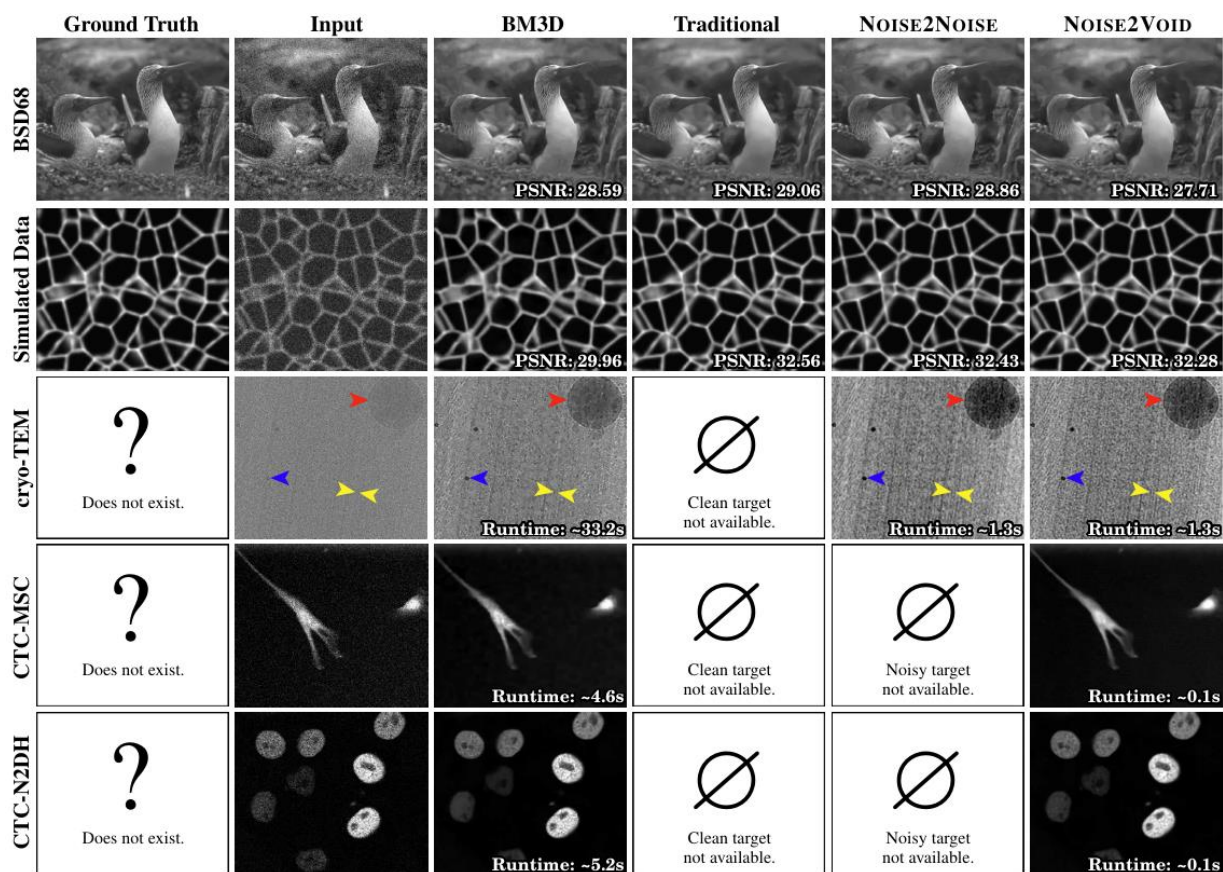
Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



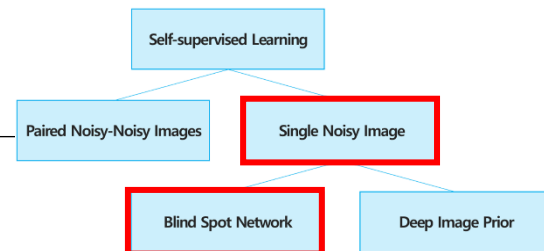
❖ Blind Spot Network: Noise2Void (2019, CVPR)

- 실험결과: Computer Vision 알고리즘보다는 우월, N2N과는 거의 유사
 - 자기 자신 픽셀 정보를 활용하지 않기에, 다른 네트워크보다 정보를 덜 사용하기 때문



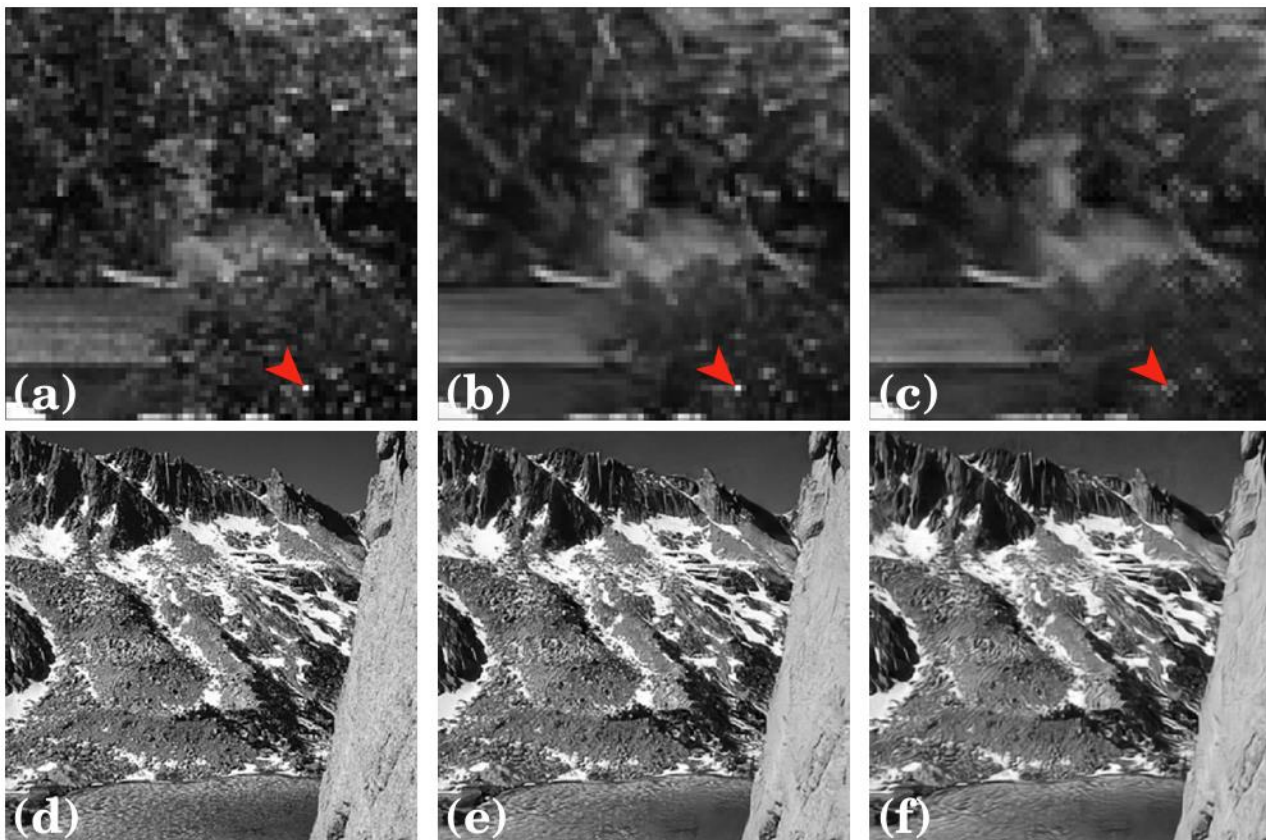
Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



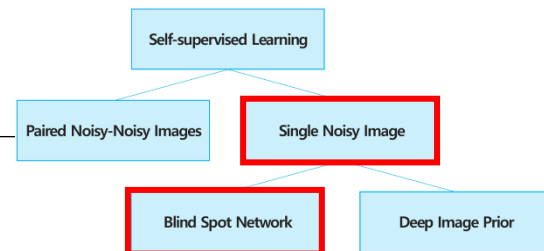
❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Failure Case①: 주변 픽셀 정보만으로 Center Pixel을 예측하기 어려운 이미지
 - 이미지 픽셀이 매우 불규칙하여 주변 정보만으로 Center Pixel을 유추하기 어려움



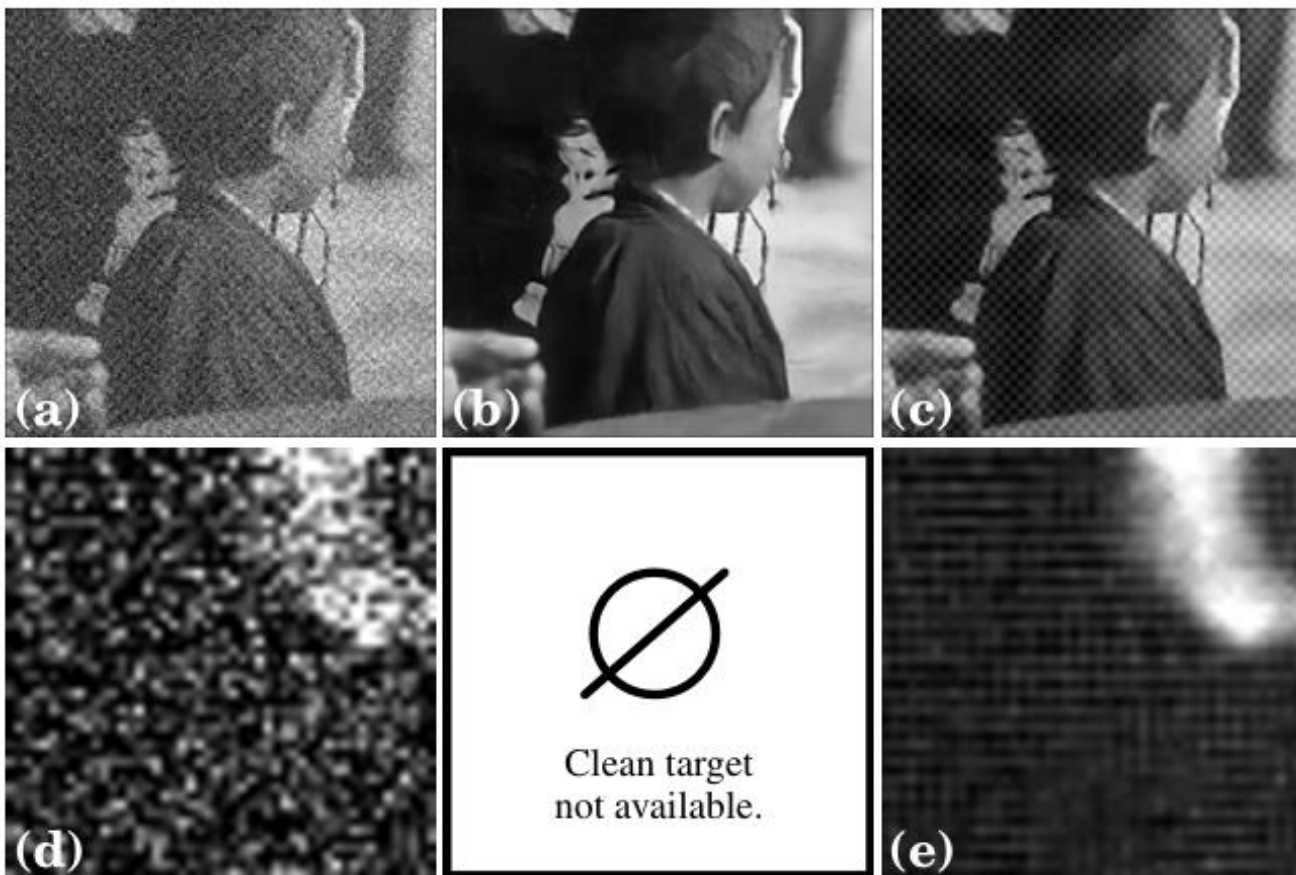
Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



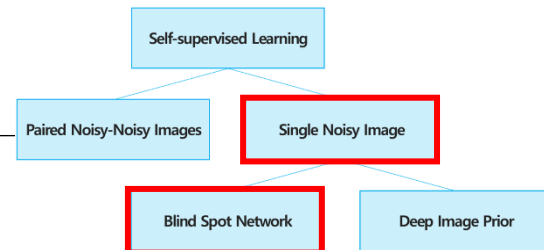
❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Failure Case② Signal과 종속적인 Noise가 포함된 이미지
 - Signal 및 Noise가 주변 픽셀과 모두 종속적이기에, BSN이 Noise도 함께 복원



Algorithms: Self-supervised Learning

Self-supervised Learning (2): Blind Spot Network



❖ Blind Spot Network: Noise2Void (2019, CVPR)

- Failure Case② Signal과 종속적인 Noise가 포함된 이미지
 - Signal 및 Noise가 주변 픽셀과 모두 종속적이기에, BSN이 Noise도 함께 복원

① Noise Pair가 불필요

② Noise에 대한 사전 지식이 불필요

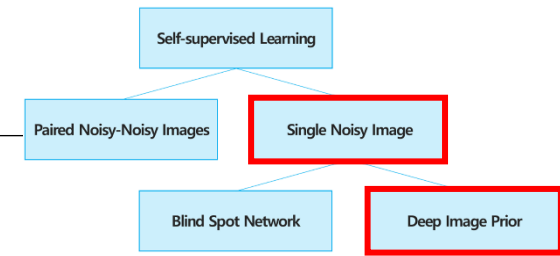
③ Noise가 Signal과 독립적인 경우 효과적 (이미지에 대한 가정 필요)

④ 복잡한 픽셀의 이미지에서는 활용이 어려움

⑤ 자기 자신의 정보를 활용하지 못하기에, 정보손실 발생

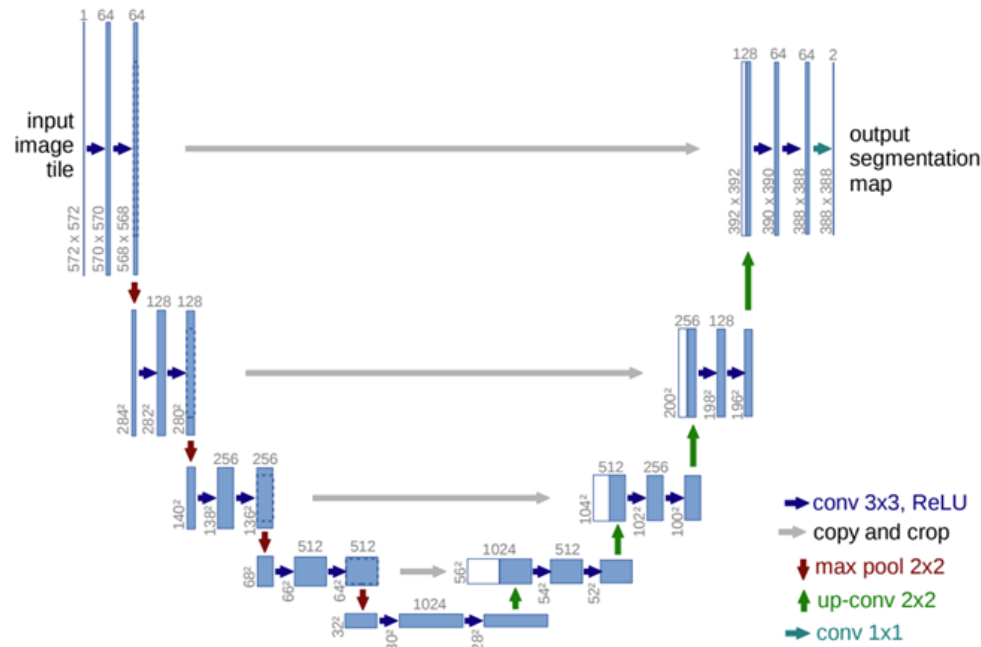
Algorithms: Supervised Learning

Self-supervised Learning (3): Deep Image Prior



❖ Deep Image Prior: Deep Image Prior (2017, CVPR)

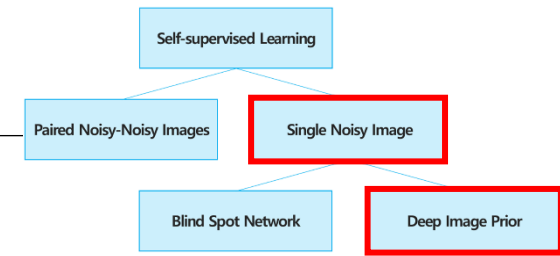
- “ 무작위로 초기화된 모델은 그 자체 만으로 Clean Image에 대한 사전지식을 갖고 있다.”
 - 인공지능 모델은 풍부한 양질의 데이터만 중요한 것이 아니다.
 - 모델 구조 그 자체만으로 충분히 Noisy Image를 Clean Image로 복원 가능



“ 모델의 사전지식으로 오직 한 장의 Noisy Image 만으로 Clean Image를 복원할 수 있다. ”

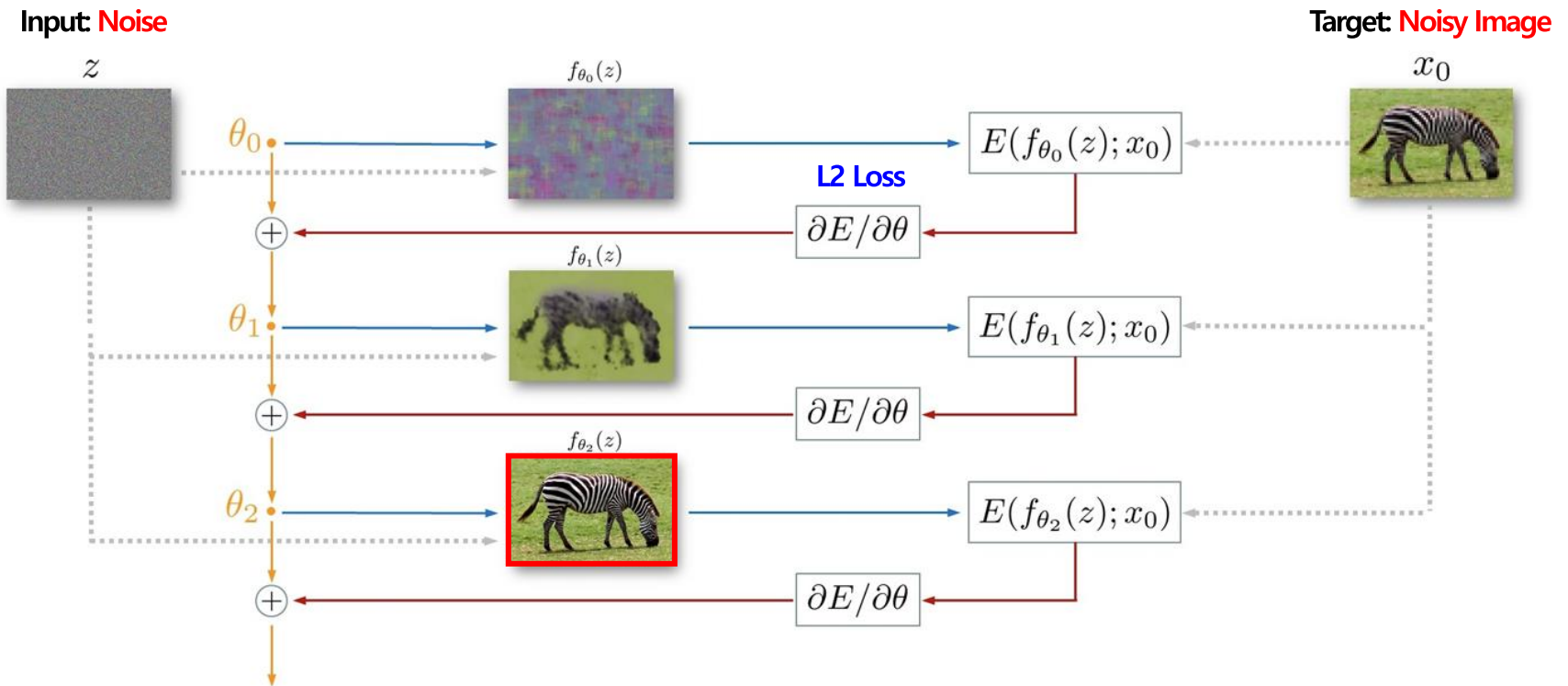
Algorithms: Supervised Learning

Self-supervised Learning (3): Deep Image Prior



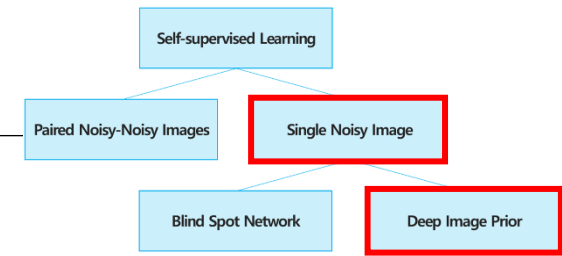
❖ Deep Image Prior: Deep Image Prior (2017, CVPR)

- Deep Image Prior: 한 장의 이미지에 여러 Iteration을 거치면 Clean Image 획득 가능



Algorithms: Supervised Learning

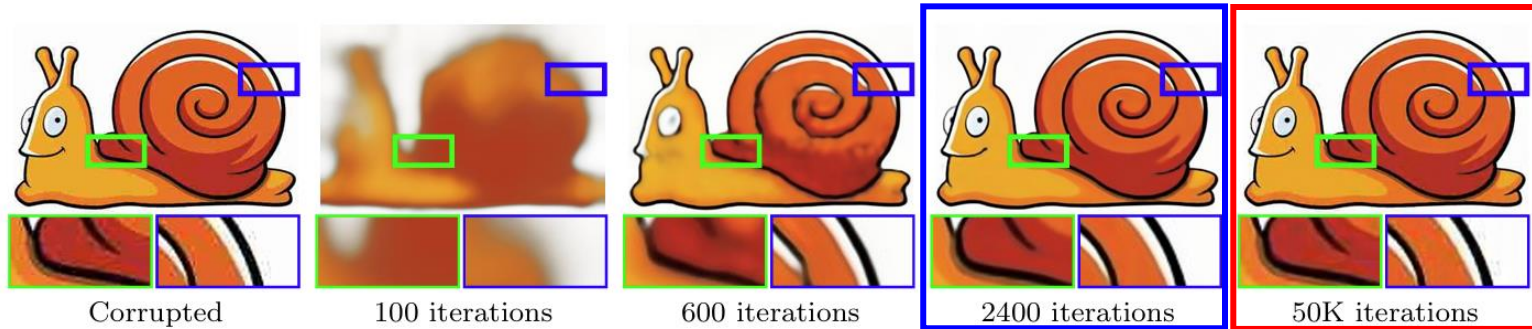
Self-supervised Learning (3): Deep Image Prior



❖ Deep Image Prior: Deep Image Prior (2017, CVPR)

Early Stopping으로 중간에 적절히 Stop 시, Clean Image 획득 가능

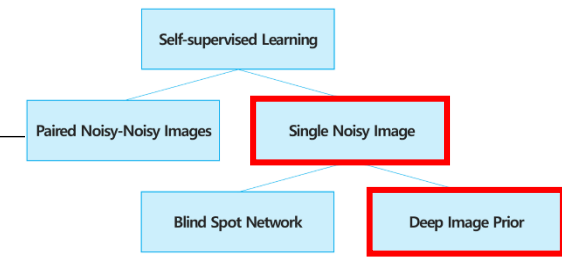
Best Iteration (Early Stopping)



지나친 학습: Noisy Image와 유사

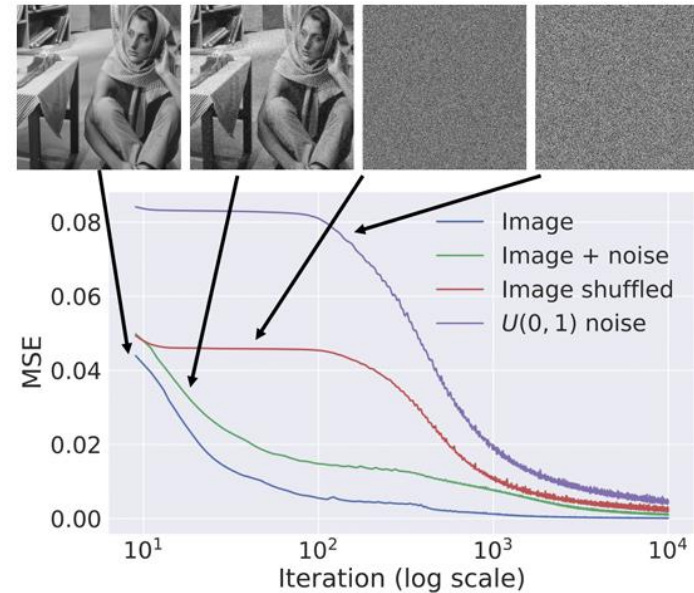
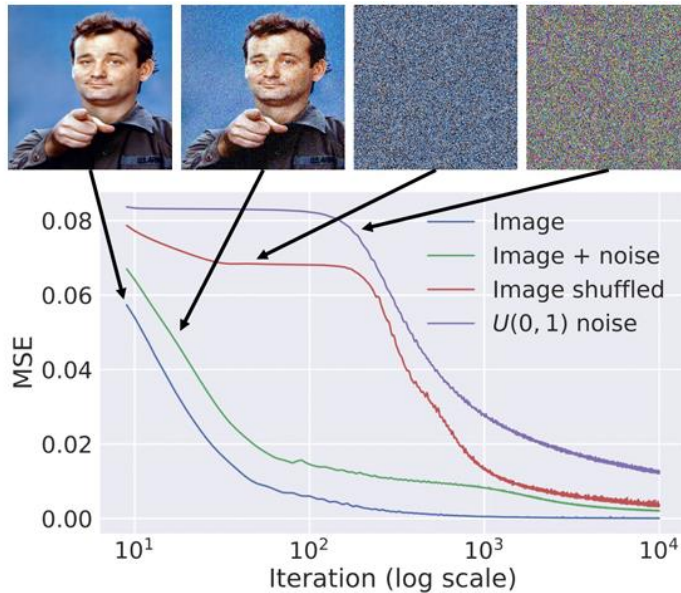
Algorithms: Supervised Learning

Self-supervised Learning (3): Deep Image Prior



❖ Deep Image Prior: Deep Image Prior (2017, CVPR)

- Early Stopping Point: Noise에 대해 Loss가 급감하는 지점
 - Loss 급감구간: 모델이 Noise에 피팅 되지 않다가 Noise에 적합되기 시작한 구간
 - Optimal Point를 찾기까지 이미지 당 평균 30분 소요

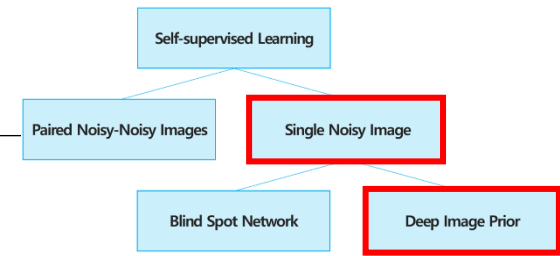


① Input이 자연스러울수록 수렴이 빠름

② Noise가 Input이더라도, 오랜 시간 후 충분히 수렴할 수 있음

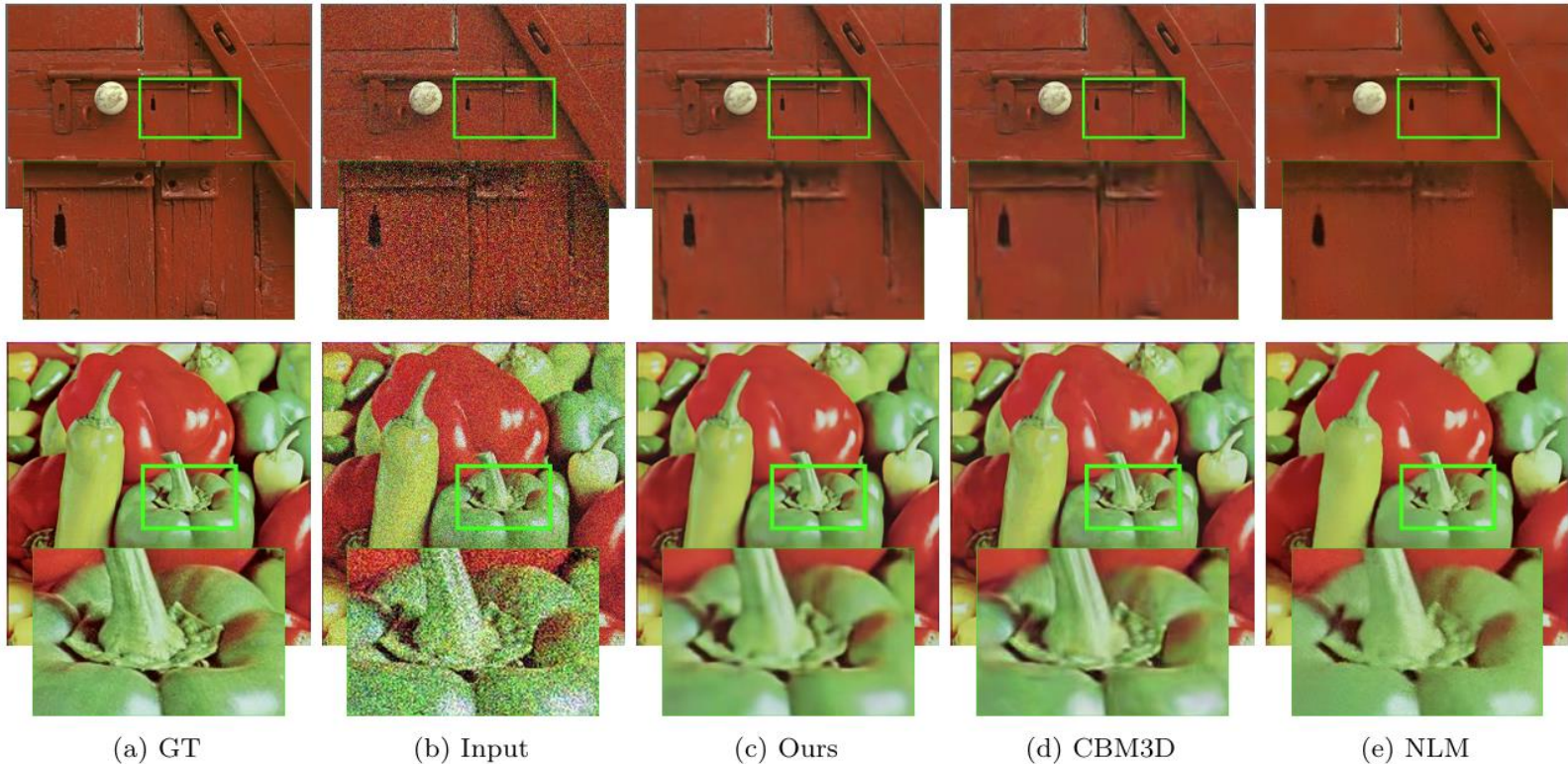
Algorithms: Supervised Learning

Self-supervised Learning (3): Deep Image Prior



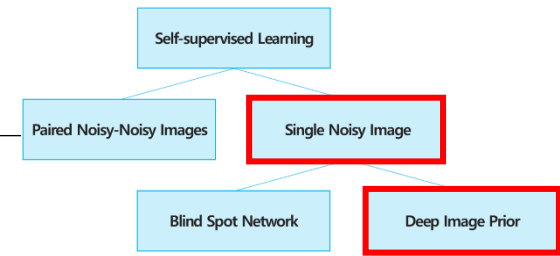
❖ Deep Image Prior: Deep Image Prior (2017, CVPR)

- 실험결과: Real-world 이미지에 우수한 Denoising 성능을 보임



Algorithms: Supervised Learning

Self-supervised Learning (3): Deep Image Prior



❖ Deep Image Prior: Deep Image Prior (2017, CVPR)

- 실험결과: Real-world 이미지에 우수한 Denoising 성능을 보임

① 오직 단 한 장의 Noisy Image만으로 Denoising 모델 학습 가능

② 이미지마다 개별 모델이 필요

③ 학습과 추론이 평균적으로 30분이라는 긴 시간동안 이루어짐

④ Early Stopping 및 Model 구조 선정에 어려움 존재

Conclusion

Conclusion

Noisy Image



Image Denoising Model

Clean Image



<Supervised Learning>

[Clean Image (0)]



Paired Noisy-Clean Images



Unpaired Noisy-Clean Images



- ① 쉽게 Noisy Image 합성 가능
- ② Noise에 대한 사전지식 필요

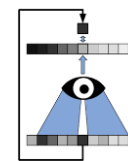
- ① Noise에 대한 사전지식 불필요
- ② 두 개의 모델에 의존

<Self-supervised Learning>

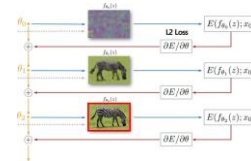
[Clean Image (X)]



Paired Noisy-Noisy Images



Single Noisy Image



- ① Noise 모델 및 가정 불필요
- ② 실제 Noisy Pair가 필요

- ① 실제 Noisy Pair 불필요
- ② Noise에 대한 학습 어려움

Reference

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Thank you!